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Outline

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2. Integral Techniques

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 - ▶ Continuous distribution
2. Integral Techniques
3. Exercises and Solutions

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 - ▶ **Discrete distribution:** countable outcomes.
 - ▶ **Continuous distribution:** uncountably infinite outcomes within intervals.

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- ▶ Normalization condition:

$$\int_{-\infty}^{\infty} f(x) dx = 1$$

Mean Value of Distributions

Discrete case:

$$\bar{x} = \sum_i x_i P(x_i)$$

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- ▶ It represents the center of mass or balance point of the probability density function.

Integral Techniques: Gaussian Integral

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$$\int_{-\infty}^{\infty} e^{-x^2} dx$$

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- ▶ Differential area transformation: $dx dy = r dr d\theta$

Integral Techniques: Calculation

Integral evaluation step-by-step:

$$I^2 = \left(\int_{-\infty}^{\infty} e^{-x^2} dx \right) \left(\int_{-\infty}^{\infty} e^{-y^2} dy \right)$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-(x^2+y^2)} dx dy$$

$$= \int_0^{2\pi} \int_0^{\infty} e^{-r^2} r dr d\theta$$

$$= \left(\int_0^{2\pi} d\theta \right) \left(\int_0^{\infty} e^{-r^2} r dr \right)$$

$$= (2\pi) \cdot \frac{1}{2} = \pi$$

$$\Rightarrow I = \sqrt{\pi}$$

Conclusion: Gaussian integral evaluates to $\sqrt{\pi}$.

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Potential questions:

- ▶ Why are integrals of odd functions zero?
- ▶ How does symmetry simplify the evaluation?

Solution: Odd Function Integral

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$$\int_{-\infty}^{\infty} x^3 e^{-x^2} dx$$

Step-by-step reasoning:

- Recognize integrand $x^3 e^{-x^2}$ is an odd function.

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Therefore,

$$\int_{-\infty}^{\infty} x^3 e^{-x^2} dx = 0$$

Solution: Even Function Integral

Evaluate integral:

$$\int_{-\infty}^{\infty} x^4 e^{-x^2} dx$$

- ▶ The integrand is even: symmetric about $x = 0$, allowing simplification:

$$2 \int_0^{\infty} x^4 e^{-x^2} dx$$

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- ▶ Substitute $u = x^2$; thus, $du = 2x dx$ or $x dx = du/2$, giving:

$$= 2 \int_0^{\infty} u^2 e^{-u} \frac{du}{2\sqrt{u}} = \int_0^{\infty} u^{3/2} e^{-u} du$$

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Integration by Parts (Detailed Explanation)

Evaluate integral:

$$\int_0^{\infty} u^{3/2} e^{-u} du$$

Integration by parts formula:

$$\int u dv = uv - \int v du$$

► First integration:

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